# Thermo hydro mechanical coupling for underground waste storage simulations

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# Outline

- •Underground waste storage concepts
- Main phenomena and modelisation
- Coupling
- Numerical difficulties
- Spatial discretisation for flows and stresses
- Simulation of the excavation of a gallery



# **Underground waste storage** concepts(1/3)



# Underground waste storage concepts (2/3)

#### ➤C waste Cell





# Underground waste storage concepts (3/3)

## Complex geometry

## Heterogeneous materials

✓ Rock at initial state or damaged rock

✓ Concrete

✓ Engineered barriers (sealing, cells closure)

✓ Fill materials

✓ Gaps

✓ Steel : container liners

Different physical behaviour

 $\checkmark$  Mechanical, thermal , chemical, hydraulic



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#### $\checkmark$ 2 components (air or H<sub>2</sub> and water ) in 2 phases (liquid and gaz) ✓ Transport equations : • Pressures Velocities $\frac{M_{gz}}{\rho_{gz}} = (1 - C_{vp}) \frac{M_{as}}{\rho_{as}} + C_{vp} \frac{M_{vp}}{\rho_{vp}}$ $p_{qz} = p_{as} + p_{vp}$ $\left(C_{vp}=\frac{p_{vp}}{p_{qq}}\right)$ $p_{lg} = p_w + p_{ad}$ • Darcy + diffusion + phase change for each phase within each phase (dissolution /vaporization) $\frac{M_{lq}}{\rho_{lq}} = \frac{K^{\text{int}} \cdot k_{lq}^{\text{rel}}(S_{lq})}{\mu_{lq}} \left( -\nabla \rho_{lq} + \rho_{lq} g \right)$ $\frac{M_{gz}}{\rho_{gz}} = \frac{K^{\text{int}} \cdot K_{gz}^{\text{rel}}(S_{lq})}{\mu_{gz}} \left( -\nabla \rho_{gz} + \rho_{gz} g \right)$ М Μ p

Main phenomena and modelisation (1/2)

## ➢Flows

$$\frac{M_{vp}}{\rho_{vp}} - \frac{M_{as}}{\rho_{as}} = -F_{vp} \nabla C_{vp}$$
$$M_{ad} - M_{w} = -F_{ad} \nabla \rho_{ad}$$



Sorption curve

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 $P_{c}=f(S_{la})=P_{az}-P_{la}$ 



# Main phenomena and modelisation (2/2)

#### Mechanical behaviour

- ✓ Plastic and brittle behaviour or the rock
- ✓ Dilatance effect at rupture stage





Axial strain

 $\checkmark$  Swelling of Engineered materials .



# Numerical difficulties (1/3)

## ➢For flows

- ✓ Non linear terms induce hyperbolic behaviour
  - Kind of equation :

$$\frac{\partial u}{\partial t} - \frac{\partial^2 u^m}{\partial x^2} = 0$$

• Stiff fronts can appear



• Big capillary effect -> No « mean » pressure



# Numerical difficulties (2/3)

## $\succ$ Example of a desaturation problem

✓ Initial state :

#### Near desaturation transition zone gas pressure tends to zero











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Reconneissence gelier

cints (conditioned)

Shear fracture

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Rorehole BFM-87

Darehole

RFM.85

Mean frequency of unloading fractures observed in the niches (see Figure 2.3.4)

Borehole BPM-85 Borehole RFM-98 (assisted)

0235-04

Overcosing batehole

SW

## Numerical difficulties (3/3)

В

Post peak damage

Fractured rock

 $0 < \gamma^{p} \leq \gamma_{P}$ 

 $\gamma_e \leq \gamma^p \leq \gamma_{ult}$ 

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Coupling (1D)	
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➢Incidence of flow on mechanical behaviour

- ✓ Standard notion of pore pressure
- ✓ Equivalent pore pressure definition for partially saturated media
  - Taking into account of interfaces in thermodynamic formulation

$$\pi = S_{\alpha} p^{\alpha} - \frac{2}{3} \int_{S_{i}}^{1} p_{c}(S) dS$$

## Incidence material deformation on flow

✓ Porosity change

✓ Straight increase of permeability with damage



$$\frac{1}{1} \xrightarrow{\text{homogenization}} D_F \xrightarrow{?} D_M$$



Coupling (2/2)	

#### Thermal evolution -> Mechanic

#### ✓ Thermal expansion



#### ➤Thermal evolution -> flow

✓ Changes in Viscosity, diffusivity coefficients
 ➢ Flow, mechanic -> thermal evolution

✓ No effect



#### Numerical methods for flow

#### Choice of principal variables

✓ Capillary pressure/gas pressure

Air mass balance ill conditioned for S=1

$$\phi \frac{\partial (\rho_a(1-S))}{\partial t} - \nabla (\rho_a k_a(S) \nabla \rho_a) = 0$$

✓ Saturation/water pressure

Air mass balance becomes :

$$\phi(1-S)\frac{\partial p_e}{\partial t} + \phi(g(S) - p_e)\frac{\partial S}{\partial t} - \nabla[p_a h(S)\nabla S] - \nabla[p_a k_a(S)\nabla p_e] = 0$$

$$P_c(S) \approx A(1-S)^{0.6} \qquad g(S) \approx p_c \qquad \text{At S=1}$$

$$k_a(S) \approx (1-S)^3 \qquad h(S) \approx A(1-S)^{2.6} \qquad \text{We have} \quad \frac{\partial S}{\partial s} = 0$$

We have  $\frac{\partial S}{\partial t} = 0$ 

 $h(S) \approx A(1-S)^{2,6}$ 

# Numerical methods for flow and mechanic : spatial discretisation

## ≻Goals

- $\checkmark$  A stable, monotone method for flow
- ✓ Easy to implement in a finite element code

Method 1 :pressure and displacement EF P2/P1 lumped formulation

• OK for consolidation modelling







# Numerical methods for flow and mechanic : spatial discretisation

## Limitations of previous formulation

Poor quadrature rule induces lack of accuracy in stresses evaluations
 Instabilities appear when simulating gas injection problem

CFV/DM (control finite volume/dual mesh)

#### Goal

✓ formulation VF compatible with architecture of EF software■Principle

- To use primal mesh for EF formulation of mechanical equations
- To construct a finite volume cell surrounding each node of the primal mesh
- To write mass balance on that polygonal cell





## CFM/DM (control finite volume/dual mesh)

Model equation

$$\frac{\partial m(u)}{\partial t} + \nabla .F(u) ; F = k(u) \nabla u$$

Mass balance:

$$A_{K} \frac{m_{K}^{n+1} - m_{K}^{n+1}}{\Delta t} + \sum_{L} T_{KL} k \left( u_{KL}^{n+1} \right) \left( u_{L}^{n+1} - u_{K}^{n+1} \right) = 0$$

#### Up winding

si 
$$u_{L}^{n+1} i u_{K}^{n+1} u_{KL}^{n+1} = u_{L}^{n+1}$$

Loop over elements of primal mesh

$$\sum_{e \in T_{K}} A_{\kappa}^{e} \frac{m_{K,e}^{n+1} - m_{K,p,e}^{n}}{\Delta t} + \sum_{e} \sum_{L \in e \neq K} T_{\kappa L}^{e} k \left( u_{\kappa L}^{n+1} \right) \left( u_{L}^{n+1} - u_{\kappa}^{n+1} \right) = 0$$

$$T_{KL}^{e} = \frac{d_{I,H}}{d_{K,I}} = -\int_{e} \nabla \lambda_{K} \cdot \nabla \lambda_{K}$$





### CFM/DM (control finite volume/dual mesh)

#### Theoretical predictions :

✓ stable, convergent and monotone for Delaunay meshes
■Example



#### For stretching H/L > 4/3 no convergence is achieved



### CFM/DM (control finite volume/dual mesh)

#### Remark about interfaces

✓ Differences between material properties can induce discontinuities.
✓ It is better to ensure constant properties over the control cell













Dogularization mathed	
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≻Main idea :

 $\checkmark$  Introduce some term bounding gradients of strain

➢Second gradient

$$\int_{OMEGA} \boldsymbol{\sigma} : \boldsymbol{\varepsilon} (u^{i}) + \int_{OMEGA} D \cdot \nabla \boldsymbol{\varepsilon} : \nabla \boldsymbol{\varepsilon}^{i} + \int_{OMEGA} f \cdot u^{i} = 0 \forall u^{i}$$

Simplified second gradient : micro gradient dilation model

 $\checkmark$  For a dilatant material we can regularise only the volumic strain

$$\int_{OMEGA} \mathbf{\sigma} : \mathbf{\varepsilon} \left( u^{i} \right) + \int_{OMEGA} D \cdot \nabla Tr \left( \varepsilon \right) \cdot \nabla Tr \left( \varepsilon^{i} \right) + \int_{OMEGA} f \cdot u^{i} = 0 \forall u^{i}$$
$$\int_{OMEGA} D \cdot \Delta u \cdot \Delta u^{i}$$



#### ➢Weak formulation

$$\int_{OMEGA} \mathbf{\sigma} : \mathbf{\epsilon} (u^{i}) + \int_{OMEGA} D \cdot \nabla \theta \cdot \nabla \theta^{i} - \int_{OMEGA} \lambda (\nabla \cdot u^{i} - \theta^{i}) + \int_{OMEGA} \lambda^{i} (\nabla \cdot u - \theta) + \int_{OMEGA} f \cdot u^{i} = 0 \forall (u^{i}, \lambda^{i})$$

Approximation spaces	и	θ	λ
Quadrangles	Q2	Q1	P0
Triangles	P2	P1	P0

➢Possible free energy displacements modes W

$$\int_{OMEGA} \sigma(w) : \varepsilon(w) = 0 \qquad \qquad \int_{e} \nabla \cdot w = 0 \quad \forall e$$

#### ➤Two ways

 $\checkmark$  Enhancing degree of discretisation for  $\lambda$ 

✓ Using penalisation

$$\int_{OMEGA} \boldsymbol{\sigma} : \boldsymbol{\epsilon} \left( u^{i} \right) + \int_{OMEGA} D \cdot \nabla \theta \cdot \nabla \theta^{i} - \int_{OMEGA} \lambda \left( \nabla \cdot u^{i} - \theta^{i} \right) + \int_{OMEGA} \lambda^{i} \left( \nabla \cdot u - \theta \right) + r \int_{OMEGA} \left( \nabla \cdot u^{i} - \theta^{i} \right) \cdot \left( \nabla \cdot u - \theta \right) + \int_{OMEGA} f \cdot u^{i} = 0$$

$$\forall \left( u^{i}, \lambda^{i} \right)$$

Benchmark Momas : Simulation of an Excavation under Brittle Hydro-mechanical behaviour

➢Cylindrical cavity

Excavation simulation

Initial conditions : anisotropic state of stress (11.0MPa, -15.4MP) ; water pressure (4.7 Mpa)



Radius of cavity : 3 meters Horizontal length for calculation domain : 60 meters Vertical length for calculation domain : 60 meters

Permeability :  $10^{-12} m. s^{-1}$ 

Time of simulation for excavation : 17 days Time of simulation for consolidation : 10 years

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Benchmark Momas : Simulation of an Excavation under Brittle Hydro-mechanical behaviour

Mechanical elasto-plastic formulation

Drucker-Prager Yield Criterion

➢Plastic rule : associated formulation

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Softening : decrease of cohesion / shear plastic deformation









#### Benchmark Momas : Localisation Phenomenon

#### Coupled modelling – After 10 years – Shear bandings





Coupled modelling Coarse mesh Coupled modelling Refined mesh

Shear bands are related to softening model
 Localisation bands are influenced by the mesh
 Hydro-mechanical coupling provides no regularisation



#### Benchmark Momas : simulation with Micro Gradient Dilation Model

Spatial discretisation with triangle elements

Visualisation of Shear bandings on Gauss Points during the excavation phasis





Band width is always greater than 2 elements

-> We can hope this result is independent of the spatial discretisation

Displacement / deconfinement

- -> Regularisation gives results for higher deconfinement ratio
- -> With a coarser mesh, simulation stops earlier

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#### Conclusions

Simulation of nuclear waste storage requires to solve non linear coupled equations in heterogeneous media

Some simulations need to solve jointly difficulties relative to two phase flow and brittle mechanical behaviours

Control finite volume/dual mesh is a reliable method for coupling darcean flows and mechanic

Regularised brittle models seem to be useful in coupled (saturated) simulations

Simplified second gradient (Micro Gradient Dilation) model gives reasonable results

