Fractal Traps & Fractional Dynamics

Pierre Inizan

Institut de Mécanique Céleste et de Calcul des Éphémérides Observatoire de Paris Paris, France

Dynamiques Fractionnaires et Applications, Pau June 2, 2010



- Object: Typical chaotic Hamiltonian systems
- Aim: Find causes of those fractional derivatives (in time)
- Motivation: Long-term behaviors of some Hamiltonian systems
- Means: Model based on studies of R. Hilfer and G.M. Zaslavsky



Practional dynamics & kinetics

- Construction of a toy-model
- Infinitesimal generators











Practional dynamics & kinetics







- Practional dynamics & kinetics
- Construction of a toy-model



| Fractional derivatives | Fractional dynamics & kinetics | |
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Construction of a toy-model

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| Fractional | integral | | | |

• Fractional derivative: generalization of the usual derivative

• $\int_{-\infty}^{t} \int_{-\infty}^{\tau_1} \dots \int_{-\infty}^{\tau_{n-1}} f(\tau_n) d\tau_n \dots d\tau_1 = \frac{1}{(n-1)!} \int_{-\infty}^{t} (t-\tau)^{n-1} f(\tau) d\tau$ $= \mathcal{I}_+^n f(t): n\text{-th primitive of } f$

• Generalization to $\delta > 0$:

$$\mathcal{I}^{\delta}_{+}f(t) = \frac{1}{\Gamma(\delta)} \int_{-\infty}^{t} (t-\tau)^{\delta-1} f(\tau) \, d\tau$$

 \rightarrow fractional integral of order δ ($\Gamma(\delta)$: Gamma function)

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| Fractional of | derivatives | | | |

• If $\omega \in (0, 1)$, derivative of order ω :

$$\mathcal{D}^{\omega}_{+}f(t) = \frac{d}{dt}\mathcal{I}^{1-\omega}_{+}f(t) = \frac{1}{\Gamma(1-\omega)}\frac{d}{dt}\int_{-\infty}^{t}(t-\tau)^{-\omega}f(\tau)\,d\tau$$

\rightarrow Liouville fractional derivative of order ω

 More convenient form (equivalent for sufficiently "good" functions):

$$\mathbf{D}_{+}^{\omega}f(t) = \frac{\omega}{\Gamma(1-\omega)} \int_{0}^{\infty} \tau^{-(1+\omega)} \left[f(t) - f(t-\tau)\right] d\tau$$

ightarrow Marchaud fractional derivative of order ω

• $\mathbf{D}^{\omega}_{+} f(t)$ exists if f bounded and locally ν -Hölderian, with $\nu > \omega$: $\forall t \in \mathbb{R}, \exists c > 0, \exists \mu > 0, |\tau| \le \mu \Rightarrow |f(t) - f(t - \tau)| \le c |\tau|^{\nu}$

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| Applicatior | าร | | | |

- Anomalous diffusion
- Memory effects
- Acoustics
- Porous media
- Phase transitions
- ...

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| Issues | | | | |

- Physical interpretation?
- Determination of ω?
 - \rightarrow True signification or synthetic useful tool?

Some attempts to answer:

- G.M. Zaslavsky: fractional kinetics in chaotic Hamiltonian systems
 - \rightarrow *interpretation*, ω
- Toy-model presented here: combination of the 2 approaches \rightarrow interpretation, ω

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Fractional dynamics: induced dynamics

Dynamics in subsystems?



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Fractional dynamics: induced dynamics

Dynamics in subsystems?



- Γ compact, $G \subset \Gamma$
- Flow $\phi^t x \rightarrow \text{leaves } G$

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Fractional dynamics: induced dynamics

Dynamics in subsystems?



- Γ compact, $G \subset \Gamma$
- Flow $\phi^t x \rightarrow$ leaves *G*!
 - Poincaré recurrence time:

 $\tau_G(x) = \inf \left\{ k \ge 1 \mid \phi^{k \triangle t} x \in G \right\}$

- Induced dynamics:
 - $S(\Delta t)x = \phi^{c_0(t)}x$

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Iterations Sⁿ(Δt): intermittent track of φ^tx

Global behaviour within G?

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Fractional dynamics: averaged dynamics

Averaged dynamics within G



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Fractional dynamics: averaged dynamics

Averaged dynamics within G



• $B \subset G \rightarrow \rho(B, t_0), \rho$ measure

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Averaged dynamics within G



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Fractional dynamics: averaged dynamics

Averaged dynamics within G



• $B \subset G \rightarrow \rho(B, t_0), \rho$ measure • $G_k(\Delta t) = \{x \in G \mid \tau_G(x) = k\Delta t\}$

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$$G_k(\Delta t) = \{x \in G \mid \tau_G(x) = k\Delta t\}$$

•
$$0 < \nu(G) < \infty, p_k(\Delta t) = rac{
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u(G)}$$

• "Infinitesimal evolution": $S(\Delta t)\rho(B, t_0) = \sum_{k=1}^{\infty} p_k(\Delta t)\phi^k$

$$=\sum_{k=1}^{\infty}p_k(\Delta t)\rho(B,t_0-k\Delta t)$$

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• "Infinitesimal evolution":

$$\begin{aligned} \mathcal{E}(\Delta t)\rho(B,t_0) &= \sum_{k=1}^{\infty} p_k(\Delta t)\phi^{k\Delta t}\rho(B,t_0) \\ &= \sum_{k=1}^{\infty} p_k(\Delta t)\rho(B,t_0-k\Delta t) \end{aligned}$$
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Frational dynamics: infinitesimal generator

• Renormalization for long-time limit: $S(\Delta t) \rightarrow \tilde{S}(\widetilde{\Delta t})$

• Infinitesimal generator of $(\tilde{S}(\Delta t))_{\Delta t>0}$:

$$\mathcal{G}\rho(B, t_0) = \lim_{\widetilde{\Delta}t \to 0} \left(\frac{\widetilde{S}(\widetilde{\Delta}t) - \mathrm{id}}{\widetilde{\Delta}t} \right) \rho(B, t_0)$$

• $\mathcal{G}
ho(B,t_0) = -\mathbf{D}^{\omega}_+
ho(B,t_0), \quad 0 < \omega \leq 1$

• $\omega = ?$

R. Hilfer:

- Foundations of fractional dynamics, Fractals, 3-3 (1995)

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Frational dynamics: infinitesimal generator

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$$\mathcal{G}\rho(\boldsymbol{B}, t_0) = \lim_{\widetilde{\Delta}t \to 0} \left(\frac{\widetilde{\boldsymbol{S}}(\widetilde{\Delta}t) - \mathrm{id}}{\widetilde{\Delta}t} \right) \rho(\boldsymbol{B}, t_0)$$

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Fractional kinetics: fractal traps



- Typical chaotic Hamiltonian systems (with classical derivatives)
 - Around kam tori, "dynamical traps"
 - Fractal structure: $P_1 \supset P_2 \supset ... \supset P_n...$ $\rightarrow V_{n+1} = \lambda_S V_n, \quad \lambda_S < 1$
 - Trapping times also auto-similar: $T_{n+1} = \lambda_T T_n, \quad \lambda_T > 1$
 - → "Sticky" zones

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Fractional kinetics: fractional equation

Kinetic description:

$$\frac{\partial^{\beta}}{\partial t^{\beta}}P(x,t) = \frac{\partial^{\alpha}}{\partial x^{\alpha}} \left(\mathcal{A}(x)P(x,t) \right), \quad 0 < \beta \leq 1, \ 0 < \alpha \leq 2$$

• Anomalous diffusion: $\langle x^2 \rangle \propto t^{\mu}$, with $\mu = \frac{2\rho}{2}$: transport exponent

0 < μ < 1: subdiffusion
 μ = 1: normal diffusion

μ > 1: superdiffusion

• Origin: dynamical traps (?) $\rightarrow \mu = \frac{|\ln \lambda_S|}{|\ln \lambda_S|}$

Justification of the fractional derivatives?

G.M. Zaslavsky:

- Hamiltonian Chaos & Fractional dynamics, Oxford University Press (2005)

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- $\mu > 1$: superdiffusion
- Origin: dynamical traps (?) $\rightarrow \mu = \frac{|\Pi| A_S|}{|n| \lambda_T}$
- Justification of the fractional derivatives?

G.M. Zaslavsky:

- Hamiltonian Chaos & Fractional dynamics, Oxford University Press (2005)

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Fractional kinetics: fractional equation

Kinetic description:

$$\frac{\partial^{\beta}}{\partial t^{\beta}} P(x,t) = \frac{\partial^{\alpha}}{\partial x^{\alpha}} \left(\mathcal{A}(x) P(x,t) \right), \quad 0 < \beta \leq 1, \ 0 < \alpha \leq 2$$

• Anomalous diffusion: $\langle x^2 \rangle \propto t^{\mu}$, with $\mu = \frac{2\beta}{\alpha}$: transport exponent

- 0 < µ < 1: subdiffusion
- $\mu = 1$: normal diffusion
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General framework



• $G \subset \Gamma$, $0 < \nu(G) < \infty$

• $\tau_G(x) = \tau_r(x) + \tau_e(x)$

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Summary

General framework



G ⊂ Γ, 0 < ν(G) < ∞
 τ_G(x) = τ_r(x) + τ_e(x)

Averaged dynamics restricted to *G*? $A \subset G$: $N_A : \mathbb{R} \longrightarrow \mathbb{R}^+$ $t \longmapsto \nu(\phi^t A \cap G)$

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• Averaged dynamics restricted to G?

 $\begin{array}{rccc} N_{\mathcal{A}} : & \mathbb{R} & \longrightarrow & \mathbb{R}^+ \\ & t & \longmapsto & \nu(\phi^t \mathcal{A} \cap \mathcal{G}) \end{array}$

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• /

• Averaged dynamics restricted to G?

$$A \subset G:$$

 $N_A: \mathbb{R} \longrightarrow \mathbb{R}^+$
 $t \longmapsto \nu(\phi^t A \cap$

 \rightarrow Evolution of *A*, restricted to *G*

G)

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| Model with | 1 trap | | | |



- Binary dynamics:
 - If a trajectory leaves G, trapped in P ⊂ Γ, during 2Δt
 - After, comes back in *G* during $k\Delta t$, $k \in \mathbb{N}^*$

 $G_0(\Delta t) = \{ x \in G | \tau_r(x) \ge \Delta t \}$ $G_1(\Delta t) = \{ x \in G | \tau_r(x) < \Delta t, \tau_{\theta}(x) = 2\Delta t \}$



•
$$p_k(\Delta t) = \frac{\nu(G_k(\Delta t))}{\nu(G)}$$

• "Mixing" property: $\forall B \in \mathcal{T}', \ \nu(B \cap G_k(\Delta t)) = p_k(\Delta t).\nu(B)$



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• $N_A(t_0) = \nu(A)$

• $N_A(t_0 + \Delta t) = \nu(A_0) = \rho_0 N_A(t_0)$

• $N_A(t_0 + 2\Delta t) = \nu(A_{00}) = \rho_0 N_A(t_0 + \Delta t)$



 $J_A(t_0 + 3\Delta t) = \nu(A_{000}) + \nu(A_{110})$ = $p_0 N_A(t_0 + 2\Delta t) + p_1 N_A(t_0)$

t₀

• $\forall n \in \mathbb{Z}, N_A(t_0+n\Delta t) = p_0 N_A(t_0+(n-1)\Delta t) + p_1 N_A(t_0+(n-3)\Delta t)$

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 $\forall n \in \mathbb{Z}, \ N_{\mathcal{A}}(t_0 + n\Delta t) = p_0 N_{\mathcal{A}}(t_0 + (n-1)\Delta t) + p_1 N_{\mathcal{A}}(t_0 + (n-3)\Delta t)$

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t₀ + 3∆t

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• Infinitesimal evolution $S(\Delta t)N_A(t_0)$: "to the next step"

Here, $\Delta t\mathbb{Z} + 2\Delta t\mathbb{Z} \equiv \Delta t\mathbb{Z} \rightarrow \text{next step: } +\Delta t$ $\rightarrow S(\Delta t)N_A(t_0) = N_A(t_0 + \Delta t)$ $= p_0N_A(t_0) + p_1N_A(t_0 - 2\Delta t)$

• Infinitesimal generator: $\mathcal{G}N_A(t_0) = \lim_{\Delta t \to 0^+} \frac{S(\Delta t)N_A(t_0) - N_A(t_0)}{\Delta t}$ $= -2p_1(0^+)\frac{d}{dt^-}N_A(t_0)$

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| Model with | more traps | | | |

• With 2 traps $(P_1, 2\Delta t)$, $(P_2, 3\Delta t)$:

• $N_A(t_0 + \Delta t) = p_0 N_A(t_0) + p_1 N_A(t_0 - 2\Delta t) + p_2 N_A(t_0 - 3\Delta t)$

• $\Delta t\mathbb{Z} + 2\Delta t\mathbb{Z} + 3\Delta t\mathbb{Z} \equiv \Delta t\mathbb{Z} \rightarrow \text{next step: } +\Delta t$

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• With \mathbb{N} traps:

• $(P_k, n_k \Delta t), n_k \in \mathbb{N}^*$

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• And if
$$\frac{n_{k_1}}{n_{k_2}} \notin \mathbb{Q}$$
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 - $\Delta t\mathbb{Z} + 2\Delta t\mathbb{Z} + 3\Delta t\mathbb{Z} \equiv \Delta t\mathbb{Z} \rightarrow \text{next step: } +\Delta t$
 - $\rightarrow S(\Delta t)N_A(t_0) = N_A(t_0 + \Delta t)$
 - Infinitesimal generator: $GN_A(t_0) = -(2p_1(0^+) + 3p_2(0^+))\frac{d}{dt^-}N_A(t_0)$
- With ℕ traps:
 - $(P_k, \underline{n_k} \Delta t), n_k \in \mathbb{N}^*$
 - $S(\Delta t)N_A(t_0) = N_A(t_0 + \Delta t) = \sum_{k \ge 0} p_k(\Delta t)N_A(t_0 n_k \Delta t)$ \rightarrow close to B. Hilfer's formula

• And if
$$\frac{n_{k_1}}{n_{k_2}} \notin \mathbb{Q}$$
?

| Fractional derivatives | Fractional dynamics & kinetics | Construction of a toy-model | Infinitesimal generators | |
|------------------------|--------------------------------|-----------------------------|--------------------------|--|
| Model with | more traps | | | |

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| Fractional derivatives | Fractional dynamics & kinetics | Construction of a toy-model | Infinitesimal generators | |
|------------------------|--------------------------------|-----------------------------|--------------------------|--|
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| Fractional derivatives | Fractional dynamics & kinetics | Construction of a toy-model | Infinitesimal generators | |
|------------------------|--------------------------------|-----------------------------|--------------------------|--|
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| Fractional derivatives | Fractional dynamics & kinetics | Construction of a toy-model ○○○○○●○ | Infinitesimal generators | |
|------------------------|--|--|--------------------------|--|
| Generaliz | ation | | | |
| • Trap | $s\left(P_k, \ T_k(\Delta t) ight), \ rac{T_{k_1}}{T_{k_2}} \notin$ | ${}^{{}_{{}^{{}_{{}^{{}}}}}}\mathbb{Q}}$ — next step $ eq$ | $\Delta t!$ | |
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$$S(\Delta t)N_{A}(t_{0}) := \sum_{k \geq 0} \rho_{k}(\Delta t)N_{A}(t_{0} - T_{k}(\Delta t))$$

| Fractional derivatives | Fractional dynamics & kinetics | Construction of a toy-model | Infinitesimal generators | |
|------------------------|--|---|--------------------------|--|
| Generaliz | ation | | | |
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| Generaliza | ation | | | |
| Traps | $\in (P_k, T_k(\Delta t)), \frac{T_{k_1}}{T_{k_2}} \notin$ | $fi \mathbb{Q} \to next step \neq$ | $\Delta t!$ | |

$$\rightarrow S(\Delta t)N_A(t_0) \neq N_A(t_0 + \Delta t)$$

• But
$$\sum_{k\geq 0} p_k(\Delta t) N_A(t_0 - n_k \Delta t) \rightarrow \sum_{k\geq 0} p_k(\Delta t) N_A(t_0 - T_k(\Delta t))$$
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| Fractional derivatives | Fractional dynamics & kinetics | Construction of a toy-model | Infinitesimal generators | |
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| Generaliz | ation | | | |
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Infinitesimal evolution $S(\Delta t) N_{A}(t_{0}) := \sum_{k \geq 0}
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| Fractional derivatives | Fractional dynamics & kinetics | Construction of a toy-model | Infinitesimal generators | |
|------------------------|---|---|--------------------------|--|
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Fractional dynamics & kinetics

Construction of a toy-model

Infinitesimal generators

Summary

Application to chaotic systems

- Zaslavsky: chaotic Hamiltonian system (with $\frac{d}{dt}$)
 - \rightarrow "averaged" dynamics?
- $V_{k+1} = \lambda_S(\Delta t) V_k$ and $T_{k+1} = \lambda_T(\Delta t) T_k$
 - Definition of $p_k(\Delta t) \rightarrow p_k(\Delta t) \propto V_k$
 - Assumption: $\lambda_{S}(\Delta t) = \lambda_{s}^{\Delta t}$ and $\lambda_{T}(\Delta t) = \lambda_{t}^{\Delta t}$
- Infinitesimal evolution:

 $S(\Delta t)N_{A}(t_{0}) = \rho_{0}(\Delta t)N_{A}(t_{0}) + (1 - \rho_{0}(\Delta t))(1 - \lambda_{s}^{\Delta t})\sum_{k \geq 0} \lambda_{s}^{k\Delta t}N_{A}(t_{0} - T_{1}(\Delta t)\lambda_{t}^{k\Delta t})$

Infinitesimal generator?

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Fractional derivatives Fractional dy 0000 00000

Fractional dynamics & kinetics

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 Fractional derivatives
 Fractional dynamics & kinetics

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 Fractional derivatives
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Infinitesimal generator?

| Fractional | derivatives |
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Fractional dynamics & kinetics

Construction of a toy-model

Outline



Practional dynamics & kinetics

Construction of a toy-model



| Fractional derivatives | Fractional dynamics & kinetics | Construction of a toy-model | Infinitesimal generators | |
|------------------------|--------------------------------|-----------------------------|--------------------------|--|
| Case $\mu > 1$ | 1 | | | |

• Zaslavsky:
$$\mu = \frac{|\ln \lambda_{\mathcal{S}}(\Delta t)|}{\ln \lambda_{\mathcal{T}}(\Delta t)} = \frac{|\ln \lambda_{s}|}{\ln \lambda_{t}}$$

• Assumption: $T_1(\Delta t) \underset{\sim}{\sim} a.\Delta t$

Theorem (Case $\mu > 1$)

If N_A is Lipschitz continuous and differentiable on \mathbb{R} , then

$$\mathcal{G}N_{\mathcal{A}}(t_0) = -\gamma \frac{d}{dt}N_{\mathcal{A}}(t_0),$$

where $\gamma = (1 - p_0(0^+)) \frac{\mu}{\mu - 1} T_1'(0)$.

| Fractional derivatives | Fractional dynamics & kinetics | Construction of a toy-model | Infinitesimal generators ●○○ | |
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| Fractional derivatives | Fractional dynamics & kinetics | Construction of a toy-model | Infinitesimal generators ●○○ | |
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| Fractional derivatives | Fractional dynamics & kinetics | Construction of a toy-model | Infinitesimal generators | |
|------------------------|--------------------------------|-----------------------------|--------------------------|--|
| Case $\mu < 1$ | 1 | | | |

• Assumption:
$$T_1(\Delta t) \underset{0^+}{\sim} b.(\Delta t)^{1/\mu}$$

Theorem (Case $\mu <$ 1)

If N_A satisfies the Hölder condition of order β and locally satisfies the Hölder condition of order δ , with $\beta < \mu < \delta$, then

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• No renormalization!

| Fractional derivatives | Fractional dynamics & kinetics | Construction of a toy-model | Infinitesimal generators | |
|------------------------|--------------------------------|-----------------------------|--------------------------|--|
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No renormalization!
| Fractional derivatives | Fractional dynamics & kinetics | Construction of a toy-model | Infinitesimal generators ○○● |
|------------------------|--------------------------------|-----------------------------|---------------------------------|
| Fractional | exponent | | |

• $\frac{\partial^{\beta}}{\partial t^{\beta}}P(x,t) = \frac{\partial^{\alpha}}{\partial x^{\alpha}} (\mathcal{A}(x)P(x,t))$ not explained with this model • But for $\frac{\partial^{\beta}}{\partial t^{\alpha}}$: "generalized shift of P(x,t) along t by Δt " (Zasl.)

• If
$$\mu > 1$$
: $\beta = 1 \rightarrow \alpha = \frac{2}{\mu} \rightarrow \frac{\partial P(x,t)}{\partial t} = \frac{\partial^{2/\mu}}{\partial x^{2/\mu}} (\mathcal{A}(x)P(x,t))$
• If $\mu > 1$: $\beta = \mu \rightarrow \alpha = 2 \rightarrow \frac{\partial^{\mu}}{\partial t^{\mu}} P(x,t) = \frac{\partial^{2}}{\partial x^{2}} (\mathcal{A}(x)P(x,t))$

| Fractional derivatives | Fractional dynamics & kinetics | Construction of a toy-model | Infinitesimal generators | |
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• If $\mu > 1$: $\beta = 1 \rightarrow \alpha = \frac{2}{\mu} \rightarrow \frac{\partial P(x,t)}{\partial t} = \frac{\partial^{2/\mu}}{\partial x^{2/\mu}} (\mathcal{A}(x)P(x,t))$ • If $\mu > 1$: $\beta = \mu \rightarrow \alpha = 2 \rightarrow \frac{\partial^{\mu}}{\partial t^{\mu}} P(x,t) = \frac{\partial^{2}}{\partial x^{2}} (\mathcal{A}(x)P(x,t))$

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- If model applied to P(x, t), compatible exponents $(\mu = \frac{2\beta}{\alpha})$:
 - If $\mu > 1$: $\beta = 1 \rightarrow \alpha = \frac{2}{\mu} \rightarrow \frac{\partial P(x,t)}{\partial t} = \frac{\partial^{2/\mu}}{\partial x^{2/\mu}} (\mathcal{A}(x)P(x,t))$

• If
$$\mu > 1$$
: $\beta = \mu \rightarrow \alpha = 2 \rightarrow \frac{\partial^{\mu}}{\partial t^{\mu}} P(x, t) = \frac{\partial^2}{\partial x^2} (\mathcal{A}(x)P(x, t))$

| Fractional derivatives | Fractional dynamics & kinetics | Construction of a toy-model | Infinitesimal generators | |
|------------------------|--------------------------------|-----------------------------|--------------------------|--|
| Fractional | exponent | | | |

•
$$\frac{\partial^{\beta}}{\partial t^{\beta}}P(x,t) = \frac{\partial^{\alpha}}{\partial x^{\alpha}} (\mathcal{A}(x)P(x,t))$$
 not explained with this model

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- Combined approach based on R. Hilfer and G.M. Zaslavsky works
- Fractional exponent: explicit expression, compatible with kinetic equation
- Limits: naive, assumptions, validity domain
- Improvements will be carried out

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Thank you !